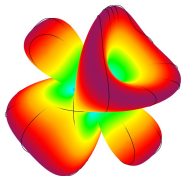


# Assessing parametric regression models with directional predictors

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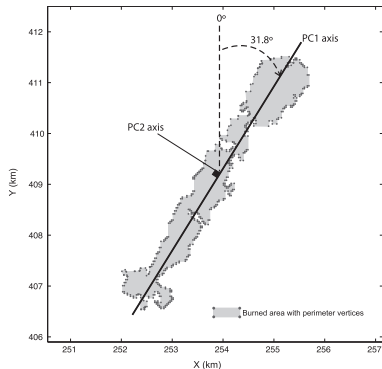
**Eduardo García-Portugués** (eduardo.garcia@usc.es)  
Ingrid Van Keilegom Rosa M. Crujeiras  
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Department of Statistics and Operations Research  
University of Santiago de Compostela

Advances in Directional Statistics, May 20, 2014



# Introduction



- Data: orientations ( $X$ ) and log-burnt areas ( $Y$ ) of 26870 wildfires in Portugal during 1985–2005.

Figure : Fire orientation.



**Barros, A. M. G., Pereira, J. M. C., and Lund, U. J. (2012).** Identifying geographical patterns of wildfire orientation: A watershed-based analysis. *Forest Ecol. Manag.*, 264, 98–107.



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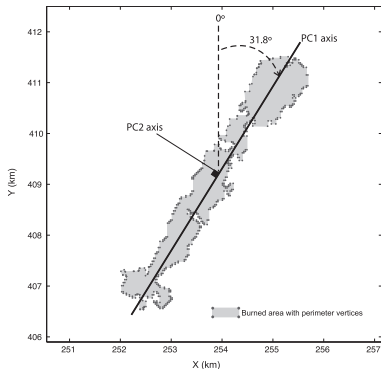


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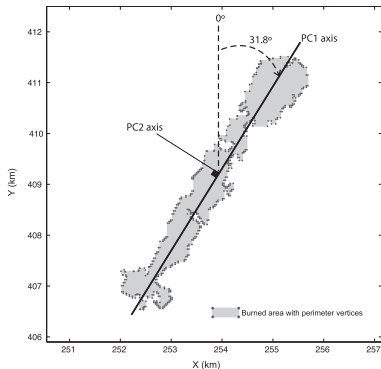


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- ▶ Data: orientations ( $\mathbf{X}$ ) and log-burnt areas ( $Y$ ) of 26870 wildfires in Portugal during 1985–2005.

- ▶ What is the relationship  $m$  between  $\mathbf{X}$  and  $Y$ ?

$$Y = m(\mathbf{X}) + \sigma(\mathbf{X})\varepsilon$$

- ▶ Two approaches for studying  $m$ :
  - ▶ Estimate  $m$  nonparametrically.
  - ▶ Check if  $m$  can be specified as a certain parametric model.

## Aim of this work

Develop new nonparametric methods for the **regression** with directional predictor  $\mathbf{X}$  and linear response  $Y$ :

- 1 Nonparametric **estimation** of the regression function  $m$ ,

$$\{(\mathbf{X}_i, Y_i)\}_{i=1}^n \implies \hat{m}_h.$$

- 2 **Goodness-of-fit** test for parametric regression models:

$$H_0 : m \in \mathcal{M}_{\Theta} = \{m_{\theta} : \theta \in \Theta\}.$$



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- 1 Nonparametric estimation of the regression function**
  - Estimator
  - Properties
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  - Testing a parametric model
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## Estimator

---

- ▶ Denote the  $q$ -sphere by  $\Omega_q = \{\mathbf{x} \in \mathbb{R}^{q+1} : \|\mathbf{x}\| = 1\}$ .
- ▶ Let  $(\mathbf{X}, Y)$  be a random variable with support in  $\Omega_q \times \mathbb{R}$ .
- ▶ Consider the regression model

$$Y = m(\mathbf{X}) + \sigma(\mathbf{X})\varepsilon \quad \text{with} \quad \begin{cases} m(\mathbf{x}) = \mathbb{E}[Y|\mathbf{X} = \mathbf{x}], \\ \sigma^2(\mathbf{x}) = \text{Var}[Y|\mathbf{X} = \mathbf{x}], \end{cases}$$

and with  $\varepsilon \perp \mathbf{X}$ ,  $\mathbb{E}[\varepsilon] = 0$  and  $\text{Var}[\varepsilon] = 1$ .





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and with  $\varepsilon \perp \mathbf{X}$ ,  $\mathbb{E}[\varepsilon] = 0$  and  $\text{Var}[\varepsilon] = 1$ .

- ▶ We want to **estimate  $m$  nonparametrically** from  $\{(\mathbf{X}_i, Y_i)\}_{i=1}^n$ .
- ▶ We will require Taylor expansions, so the first **condition** is

**LL1** Extend  $m$  and  $f$  from  $\Omega_q$  to  $\mathbb{R}^{q+1} \setminus \{\mathbf{0}\}$  by  $m(\mathbf{x}) \equiv m(\mathbf{x}/\|\mathbf{x}\|)$  and  $f(\mathbf{x}) \equiv f(\mathbf{x}/\|\mathbf{x}\|)$ .  $m$  is third and  $f$  is twice continuously differentiable and  $f$  is bounded away from zero.

- ▶ Let  $\mathbf{x}, \mathbf{X}_i \in \Omega_q$ . The one term Taylor expansion of  $m$  is:

$$m(\mathbf{X}_i) = m(\mathbf{x}) + \nabla m(\mathbf{x})^T (\mathbf{X}_i - \mathbf{x}) + \mathcal{O}(\|\mathbf{X}_i - \mathbf{x}\|^2)$$

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with  $\mathbf{B}_q = (\mathbf{b}_1, \dots, \mathbf{b}_q)_{(q+1) \times q}$  such that  $\mathbf{B}_q \mathbf{B}_q^T = \mathbf{I}_{q+1} - \mathbf{x}\mathbf{x}^T$ ,  $\beta_0 = m(\mathbf{x})$  and  $\beta_{1:(q+1)} = \mathbf{B}_q^T \nabla m(\mathbf{x})$ .

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- This motivates the weighted minimum least squares problem ( $p = 0$  for local constant and  $p = 1$  for local linear)

$$\min_{\beta \in \mathbb{R}^{q+1}} \sum_{i=1}^n \left( Y_i - \beta_0 - \delta_{p,1} (\beta_1, \dots, \beta_q)^T \mathbf{B}_q^T (\mathbf{X}_i - \mathbf{x}) \right)^2 L_h(\mathbf{x}, \mathbf{X}_i).$$

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- ▶ The solution is given by

$$\hat{m}_{h,p}(\mathbf{x}) = \hat{\beta}_0 = \mathbf{e}_{1,p}^T \left( \boldsymbol{\mathcal{X}}_{\mathbf{x},p}^T \mathbf{W}_{\mathbf{x}} \boldsymbol{\mathcal{X}}_{\mathbf{x},p} \right)^{-1} \boldsymbol{\mathcal{X}}_{\mathbf{x},p}^T \mathbf{W}_{\mathbf{x}} \mathbf{Y} = \sum_{i=1}^n W_p^n(\mathbf{x}, \mathbf{X}_i) Y_i,$$

where  $\mathbf{W}_{\mathbf{x}} = \text{diag}(L_h(\mathbf{x}, \mathbf{X}_1), \dots, L_h(\mathbf{x}, \mathbf{X}_n))$  and

$$\mathbf{Y} = \begin{pmatrix} Y_1 \\ \vdots \\ Y_n \end{pmatrix}, \boldsymbol{\mathcal{X}}_{\mathbf{x},0} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}, \boldsymbol{\mathcal{X}}_{\mathbf{x},1} = \begin{pmatrix} 1 & (\mathbf{X}_1 - \mathbf{x})^T \mathbf{B}_q \\ \vdots & \vdots \\ 1 & (\mathbf{X}_n - \mathbf{x})^T \mathbf{B}_q \end{pmatrix}.$$



## Alternative proposal

► Technical details



**Di Marzio, M., Panzera, A., and Taylor, C. C. (2014).** Nonparametric regression for spherical data *J. Amer. Statist. Assoc.* (to appear).

- Taylor expansion based on the tangent–normal decomposition  $\mathbf{X}_i = \mathbf{x} \cos(\theta_{\mathbf{x},i}) + \boldsymbol{\xi}_{\mathbf{x},i} \sin(\theta_{\mathbf{x},i})$ , where  $\theta_{\mathbf{x},i} \in [0, 2\pi)$ ,  $\mathbf{x}, \boldsymbol{\xi}_{\mathbf{x},i} \in \Omega_q$  and  $\boldsymbol{\xi}_{\mathbf{x},i} \perp \mathbf{x}$ :

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- Weighted minimum least squares problem

$$\min_{\boldsymbol{\beta} \in \mathbb{R}^{q+2}} \sum_{i=1}^n \left( Y_i - \beta_0 - (\beta_1, \dots, \beta_{q+1})^T \theta_{\mathbf{x},i} \boldsymbol{\xi}_{\mathbf{x},i} \right)^2 K_{\kappa}(\cos(\theta_{\mathbf{x},i})),$$

$$\boldsymbol{\mathcal{X}}_{\mathbf{x},1} = \begin{pmatrix} 1 & \theta_{\mathbf{x},1} \boldsymbol{\xi}_{\mathbf{x},1}^T \\ \vdots & \vdots \\ 1 & \theta_{\mathbf{x},n} \boldsymbol{\xi}_{\mathbf{x},n}^T \end{pmatrix}_{n \times (q+1)}, \quad \boldsymbol{\mathcal{W}}_{\mathbf{x}} = \text{diag}(K_{\kappa}(\cos(\theta_{\mathbf{x},1})), \dots, K_{\kappa}(\cos(\theta_{\mathbf{x},n}))).$$





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- ▶  $\boldsymbol{\mathcal{X}}_{\mathbf{x},1}^T \boldsymbol{\mathcal{W}}_{\mathbf{x}} \boldsymbol{\mathcal{X}}_{\mathbf{x},1}$  is singular, so a pseudo–inverse is required.
- ▶ Results for bias, variance and normality are equivalent to ours.



## Remarkable cases

---

- 1 **Local constant** ( $p = 0$ ), the Nadaraya–Watson estimator:

$$\hat{m}_{h,0}(\mathbf{x}) = \sum_{i=1}^n W_p^n(\mathbf{x}, \mathbf{X}_i) Y_i = \frac{\sum_{i=1}^n L_h(\mathbf{x}, \mathbf{X}_i) Y_i}{\sum_{j=1}^n L_h(\mathbf{x}, \mathbf{X}_j)}.$$



**Wang, X., Zhao, L., and Wu, Y. (2000).** Distribution free laws of the iterated logarithm for kernel estimator of regression function based on directional data. *Chinese Ann. Math. Ser. B*, 21(4):489–498.



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- ② **Circular case** ( $q = 1$ ): set  $\mathbf{x} = (\cos \theta, \sin \theta)$ ,  $\mathbf{X}_i = (\cos \Theta_i, \sin \Theta_i)$  and  $\kappa = h^{-2}$ , for  $\theta, \Theta_i \in [0, 2\pi)$ . For  $p = 1$ ,  $\mathbf{B}_1 = (-\sin \theta, \cos \theta)^T$  and  $\mathbf{B}_1 \perp \mathbf{x}$ :

$$\mathcal{X}_{\mathbf{x},1} = \begin{pmatrix} 1 & (\mathbf{X}_1 - \mathbf{x})^T \mathbf{B}_1 \\ \vdots & \vdots \\ 1 & (\mathbf{X}_n - \mathbf{x})^T \mathbf{B}_1 \end{pmatrix} = \begin{pmatrix} 1 & \sin(\theta - \Theta_1) \\ \vdots & \vdots \\ 1 & \sin(\theta - \Theta_n) \end{pmatrix}.$$



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$$\min_{\beta \in \mathbb{R}^2} \sum_{i=1}^n (Y_i - \beta_0 - \beta_1 \sin(\theta - \Theta_i))^2 L_\kappa(\kappa(1 - \cos(\theta - \Theta_i))).$$



**Di Marzio, M., Panzera, A., and Taylor, C. C. (2009).** Local polynomial regression for circular predictors. *Statist. Probab. Lett.*, 79(19):2066–2075.



# Properties

## Theorem (Conditional bias and variance)

Under assumptions LL1–LL4, for  $\mathbf{x} \in \Omega_q$  (uniformly),

$$\mathbb{E}[\hat{m}_{h,p}(\mathbf{x}) | \mathbf{X}_1, \dots, \mathbf{X}_n] = m(\mathbf{x}) + b_q(L)B_p(\mathbf{x})h^2 + o_{\mathbb{P}}(h^2),$$

$$\text{Var}[\hat{m}_{h,p}(\mathbf{x}) | \mathbf{X}_1, \dots, \mathbf{X}_n] = \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q f(\mathbf{x})} \sigma^2(\mathbf{x}) + o_{\mathbb{P}}\left((nh^q)^{-1}\right),$$

$$\text{where } B_p(\mathbf{x}) = \begin{cases} \frac{2}{q} \frac{\nabla f(\mathbf{x})^T}{f(\mathbf{x})} \nabla m(\mathbf{x}) + \frac{1}{q} \text{tr}[\mathcal{H}_m(\mathbf{x})], & p = 0, \\ \frac{1}{q} \text{tr}[\mathcal{H}_m(\mathbf{x})], & p = 1. \end{cases}$$

### ► Conditions

LL2  $\sigma^2$  is uniformly continuous and bounded away from zero.

LL3 The kernel  $L : [0, \infty) \rightarrow [0, \infty)$  is a bounded function with exponential decay ( $L(r) \leq Me^{-\alpha r}$ ).

LL4 The positive sequence  $h = h_n$  satisfies  $h \rightarrow 0$  and  $nh^q \rightarrow \infty$ .



**Ruppert, D. and Wand, M. P. (1994).** Multivariate locally weighted least squares regression. *Ann. Statist.*, 22(3):1346–1370.

- From the conditional bias and variance, expansions for conditional MSE, MISE and  $h_{AMISE}$  bandwidth follow. ► Simulations bandwidth selection

### Corollary (Equivalent kernel, as in Fan and Gijbels (1996))

Under assumptions LL1–LL4, the weights in the estimator  $\hat{m}_{h,p}(\mathbf{x}) = \sum_{i=1}^n W_p^n(\mathbf{x}, \mathbf{X}_i) Y_i$  at  $\mathbf{x} \in \Omega_q$  satisfy (uniformly)

$$W_p^n(\mathbf{x}, \mathbf{X}_i) = \frac{1}{nh^q \lambda_q(L) f(\mathbf{x})} L \left( \frac{1 - \mathbf{x}^T \mathbf{X}_i}{h^2} \right) (1 + o_{\mathbb{P}}(1)).$$



**Fan, J. and Gijbels, I. (1996).** *Local polynomial modelling and its applications.* Chapman & Hall.

### Theorem (Asymptotic normality)

Under assumptions LL1–LL4, for  $\mathbf{x} \in \Omega_q$  such that for a  $\delta > 0$   $\mathbb{E}[(Y - m(\mathbf{X}))^{2+\delta} | \mathbf{X} = \mathbf{x}] < \infty$ ,

$$\sqrt{nh^q} (\hat{m}_{h,p}(\mathbf{x}) - m(\mathbf{x}) - b_q(L) B_p(\mathbf{x}) h^2) \xrightarrow{d} \mathcal{N} \left( 0, \frac{\lambda_q(L^2) \lambda_q(L)^{-2}}{f(\mathbf{x})} \sigma^2(\mathbf{x}) \right).$$



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## Testing a parametric model

---

- ▶ We want to check  $H_0 : m \in \mathcal{M}_\Theta = \{m_\theta : \theta \in \Theta\}$ .
- ▶ No test available in the literature for checking this hypothesis.



**González-Manteiga, W. and Crujeiras, R. M. (2013).** An updated review of goodness-of-fit tests for regression models. *TEST*, 22(3):361–411.



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- ▶ We consider as statistic the smoothed weighted  $\mathcal{L}^2$ -distance between  $\hat{m}_{h,p}$  and  $m_{\hat{\theta}}$ :

$$T_n = \int_{\Omega_q} (\hat{m}_{h,p}(\mathbf{x}) - \mathcal{L}_{h,p} m_{\hat{\theta}}(\mathbf{x}))^2 \hat{f}_h(\mathbf{x}) w(\mathbf{x}) \omega_q(d\mathbf{x}).$$

where  $\mathcal{L}_{h,p} m(\mathbf{x}) = \sum_{i=1}^n W_n^p(\mathbf{x}, \mathbf{X}_i) m(\mathbf{X}_i)$ .



**Alcalá, J. T., Cristóbal, J. A., and González-Manteiga, W. (1999).** Goodness-of-fit test for linear models based on local polynomials. *Statist. Probab. Lett.*, 42(1):39–46.



**Härdle, W. and Mammen, E. (1993).** Comparing nonparametric versus parametric regression fits. *Ann. Statist.*, 21(4):1926–1947.



## Limit distribution

### Theorem (Limit distribution of $T_n$ ) ▶ Sketch of the proof

Under conditions LL1–LL4, GF1–GF2 and under  $H_0 : m \in \mathcal{M}_\Theta$ ,

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2).$$

#### ▶ Conditions

GF1 Under  $H_0$ , there exists a  $\hat{\theta}$  such that  $\hat{\theta} - \theta_0 = \mathcal{O}_{\mathbb{P}}(n^{-\frac{1}{2}})$ .

GF2  $m_\theta$  is continuously differentiable as a function of  $\theta$ , being this derivative also continuous for  $\mathbf{x} \in \Omega_q$ .



# Limit distribution

## Theorem (Limit distribution of $T_n$ ) ▶ Sketch of the proof

Under conditions LL1–LL4, GF1–GF2 and under  $H_0 : m \in \mathcal{M}_\Theta$ ,

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2).$$

### ▶ Conditions

### ▶ Constants

$$\begin{aligned} \nu^2 &= \int_{\Omega_q} \sigma^4(\mathbf{x})w(\mathbf{x})^2\omega_q(d\mathbf{x}) \\ &\times \gamma_q \lambda_q(L)^{-4} \int_0^\infty r^{\frac{q}{2}-1} \left\{ \int_0^\infty \rho^{\frac{q}{2}-1} L(\rho)\varphi_q(r, \rho) d\rho \right\}^2 dr \end{aligned}$$

$$\varphi_q(r, \rho) = \begin{cases} L\left(r + \rho - 2(r\rho)^{\frac{1}{2}}\right) + L\left(r + \rho + 2(r\rho)^{\frac{1}{2}}\right), & q = 1, \\ \int_{-1}^1 (1 - u^2)^{\frac{q-3}{2}} L\left(r + \rho - 2u(r\rho)^{\frac{1}{2}}\right) du, & q \geq 2. \end{cases}$$



## Limit distribution

### Theorem (Limit distribution of $T_n$ ) ▶ Sketch of the proof

Under conditions LL1–LL4, GF1–GF2 and under  $H_0 : m \in \mathcal{M}_\Theta$ ,

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2).$$

▶ **Conditions**

▶ **Constants**

$$\begin{aligned} \nu^2 &= \int_{\Omega_q} \sigma^4(\mathbf{x})w(\mathbf{x})^2\omega_q(d\mathbf{x}) \\ &\quad \times \gamma_q \lambda_q(L)^{-4} \int_0^\infty r^{\frac{q}{2}-1} \left\{ \int_0^\infty \rho^{\frac{q}{2}-1} L(\rho)\varphi_q(r, \rho) d\rho \right\}^2 dr \end{aligned}$$

- ▶ If  $L$  is the **von Mises kernel**,  $\nu^2 = \int_{\Omega_q} \sigma^4(\mathbf{x})w(\mathbf{x})^2\omega_q(d\mathbf{x}) \times (8\pi)^{-\frac{q}{2}}$ .



## Power under local alternatives

- ▶ We consider a function  $g : \Omega_q \rightarrow \mathbb{R}$  such that  $g \notin \mathcal{M}_\Theta$  and the Pitman local alternative:

$$H_{1L} : m(\mathbf{x}) = m_{\theta_0}(\mathbf{x}) + (nh^{\frac{q}{2}})^{-\frac{1}{2}} g(\mathbf{x}), \forall \mathbf{x} \in \Omega_q.$$

### Theorem (Power under local alternatives)

Under conditions LL1–LL4, GF2–GF4 and under  $H_{1L}$ ,

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N} \left( \int_{\Omega_q} g(\mathbf{x})^2 f(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}), 2\nu^2 \right).$$

- ▶ **Conditions**

GF3 Under  $H_{1L}$ , there exists a  $\hat{\theta}$  such that  $\hat{\theta} - \theta_0 = \mathcal{O}_{\mathbb{P}}(n^{-\frac{1}{2}})$ .

GF4 The function  $g$  is continuous.



## Calibration in practice

### Algorithm (Testing procedure) ▶ Bootstrap consistency

Let  $\{(\mathbf{X}_i, Y_i)\}_{i=1}^n$  be a random sample. To test  $H_0 : m \in \mathcal{M}_{\Theta}$ :

- 1 Compute  $\hat{\theta}$ , and set  $\hat{\varepsilon}_i = Y_i - \hat{m}_{h,p}(\mathbf{X}_i)$ ,  $i = 1, \dots, n$ .
- 2 Compute

$$T_n = \int_{\Omega_q} (\hat{m}_{h,p}(\mathbf{x}) - \mathcal{L}_{h,p} m_{\hat{\theta}}(\mathbf{x}))^2 \hat{f}_h(\mathbf{x}) w(\mathbf{x}) \omega_q(d\mathbf{x}).$$

- 3 Bootstrap strategy. For  $b = 1, \dots, B$ :
  - ▶ Set  $Y_i^* = m_{\hat{\theta}}(\mathbf{X}_i) + \hat{\varepsilon}_i V_i$ ,  $i = 1, \dots, n$ , where  $V_i$  are golden binary random variables.
  - ▶ Compute  $\hat{\theta}^*$  from  $\{(\mathbf{X}_i, Y_i^*)\}_{i=1}^n$  and set

$$T_n^{*b} = \int_{\Omega_q} (\hat{m}_{h,p}^*(\mathbf{x}) - \mathcal{L}_{h,p} m_{\hat{\theta}^*}(\mathbf{x}))^2 \hat{f}_h(\mathbf{x}) w(\mathbf{x}) \omega_q(d\mathbf{x}).$$

- 4 Estimate the  $p$ -value as  $\# \{T_n^{*b} \leq T_n\} / B$ .



## Simulation study

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**Scenarios:**  $Y = m_{\theta}(\mathbf{X}) + \sigma(\mathbf{X})\varepsilon$ .

- ▶ Density of  $\mathbf{X}$ : 6 different directional densities.
- ▶ Regression function  $m_{\theta}$ : 12 new directional-linear models.
- ▶ Noise  $\varepsilon \sim \mathcal{N}(0, 1)$ ,  $\sigma(\mathbf{x})$  constant and variable (heteroskedastic).
- ▶ Deviations from  $H_0 : m \in \mathcal{M}_{\Theta}$  constructed by sampling from  $m_{\delta}(\mathbf{x}) = m_{\theta_0}(\mathbf{x}) + \delta\Delta(\mathbf{x})$ . [▶ Details](#)

### Simulation setting:

- ▶ Sample sizes  $n = 100, 250, 500$ , dimensions  $q = 1, 2, 3$ , local constant ( $p = 0$ ) and linear ( $p = 1$ ) estimators.
- ▶  $B = 1000$  bootstrap replicates and  $M = 1000$  Monte Carlo trials for evaluating the empirical size/power of the test.
- ▶ Bandwidth grid for exploring its effect.



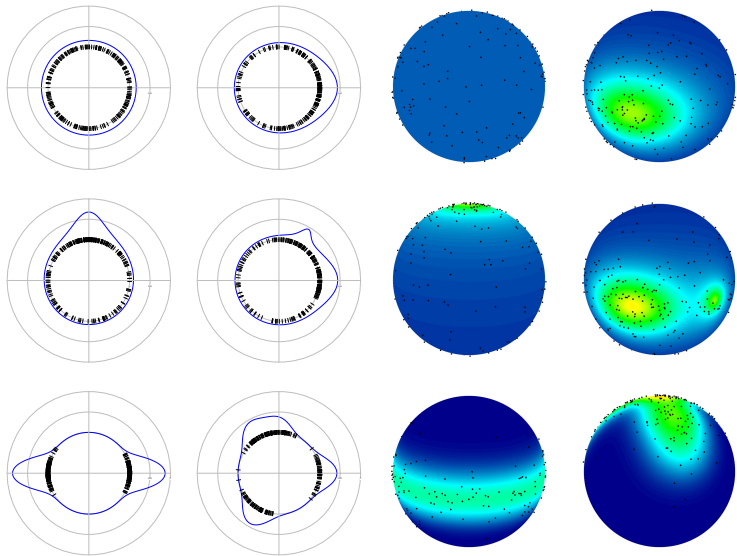


Figure : Densities D1 to D6 for the circular and spherical cases.

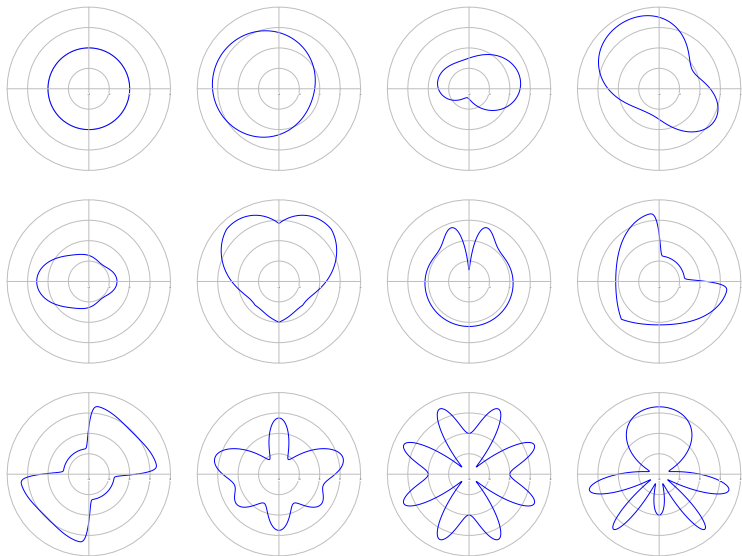


Figure : Models M1 to M12 for the circular case ( $q = 1$ ). [▶ Details](#)

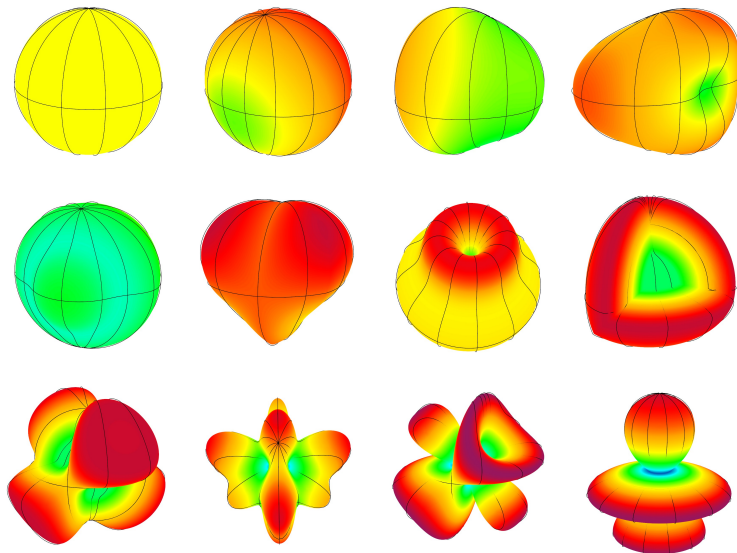


Figure : Models M1 to M12 for the spherical case ( $q = 2$ ). [▶ Details](#)

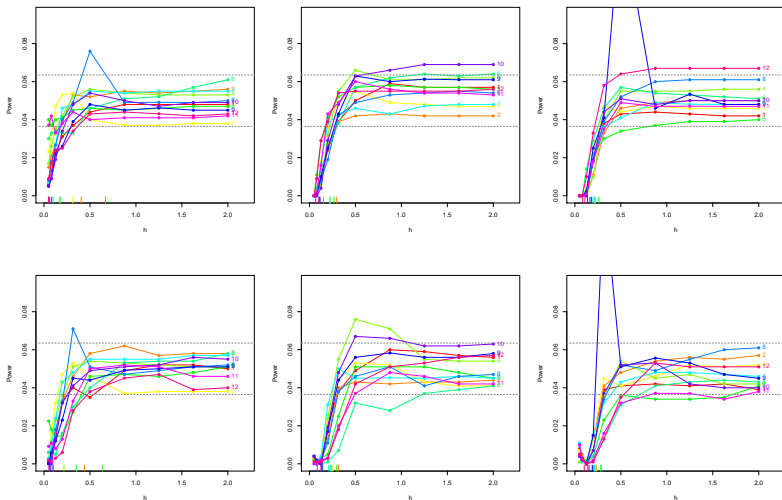


Figure : Empirical sizes for  $\alpha = 0.05$  with  $p = 0$  (upper row) and  $p = 1$  (lower row). Columns:  $q = 1, 2, 3$  and  $n = 100, 250, 500$ . [▶ More sizes](#)

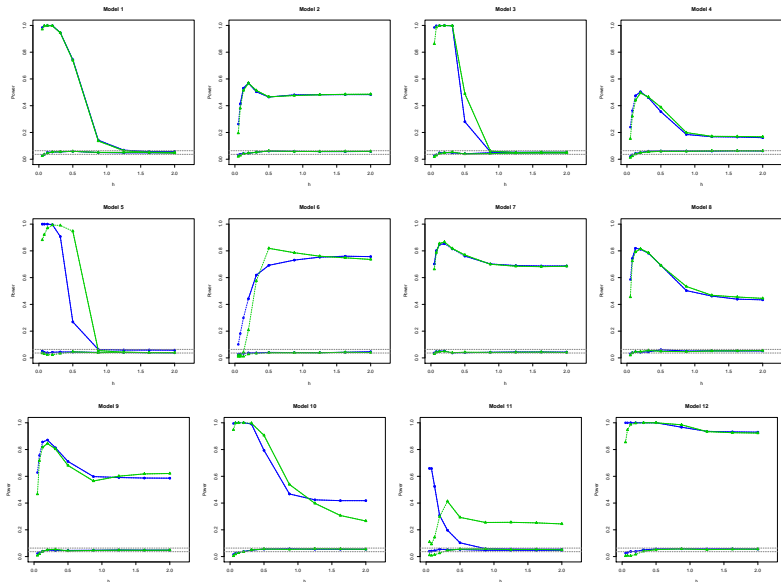


Figure : Powers for  $\alpha = 0.05$  with  $p = 0$  (blue) and  $p = 1$  (green), for  $q = 1$  and  $n = 250$ . [▶ More powers](#)



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  - Estimator
  - Properties
- 2 **Goodness-of-fit tests for models with directional predictor**
  - Testing a parametric model
  - Calibration in practice
  - Simulation study
- 3 **Data application**



# Wildfire orientation

- Data: 102 averaged orientations and log-burnt areas of the wildfires in each watershed of Portugal in 1985–2005.

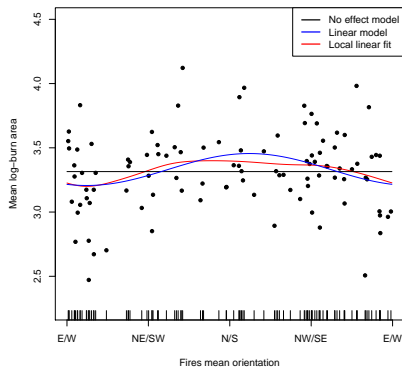


Figure : Wildfires data with two parametric fits and a local linear fit.



**Barros, A. M. G., Pereira, J. M. C., and Lund, U. J. (2012).** Identifying geographical patterns of wildfire orientation: A watershed-based analysis. *Forest Ecol. Manag.*, 264, 98–107.



# Wildfire orientation

- ▶ Data: 102 averaged orientations and log-burnt areas of the wildfires in each watershed of Portugal in 1985–2005.
- ▶ No effect model:

$$m(\mathbf{x}) = c.$$

- ▶ FDR  $p$ -values: 0.027 (loc. const.) and 0.047 (loc. lin.).
- ▶ **Evidence to reject the model.**

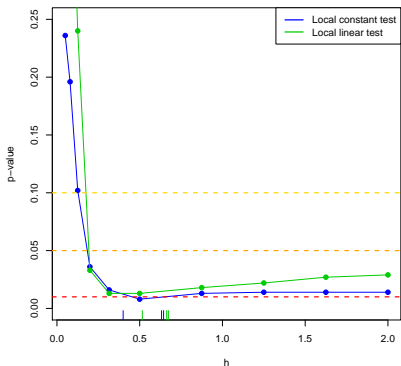


Figure :  $p$ -values of the goodness-of-fit test for no effect model.



**Barros, A. M. G., Pereira, J. M. C., and Lund, U. J. (2012).** Identifying geographical patterns of wildfire orientation: A watershed-based analysis. *Forest Ecol. Manag.*, 264, 98–107.





## Wildfire orientation

- ▶ Data: 102 averaged orientations and log–burnt areas of the wildfires in each watershed of Portugal in 1985–2005.
- ▶ Linear model:

$$m(\mathbf{x}) = c + \beta^T \mathbf{x}$$

- ▶ FDR  $p$ -values: 0.230 (loc. const.) and 0.204 (loc. lin.).
- ▶ **No evidence to reject the model.**



**Barros, A. M. G., Pereira, J. M. C., and Lund, U. J. (2012).** Identifying geographical patterns of wildfire orientation: A watershed-based analysis. *Forest Ecol. Manag.*, 264, 98–107.

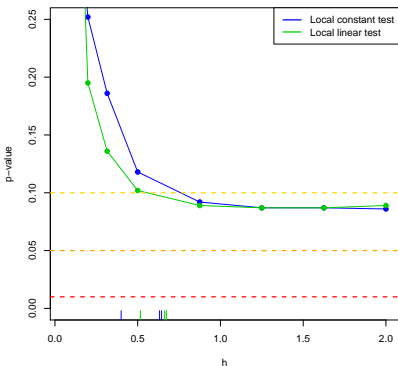


Figure :  $p$ -values of the goodness-of-fit test for linear model.



## Wildfire orientation

- ▶ Data: 102 averaged orientations and log-burnt areas of the wildfires in each watershed of Portugal in 1985–2005.
- ▶ Linear model:
$$m(\theta) = c + \beta_1 \cos(\theta) + \beta_2 \sin(\theta)$$
- ▶ FDR  $p$ -values: 0.230 (loc. const.) and 0.204 (loc. lin.).
- ▶ **No evidence to reject the model.**



**Barros, A. M. G., Pereira, J. M. C., and Lund, U. J. (2012).** Identifying geographical patterns of wildfire orientation: A watershed-based analysis. *Forest Ecol. Manag.*, 264, 98–107.

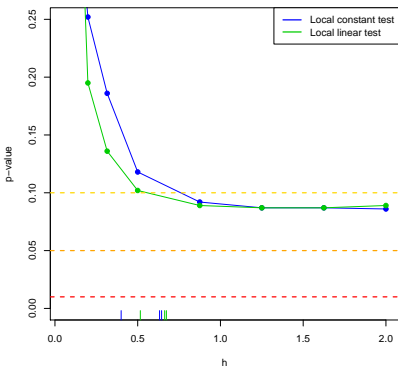


Figure :  $p$ -values of the goodness-of-fit test for linear model.



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## Some notes of caution in smoothing

- Holes in the support and local linear estimation.** Local linear smoothing can be worse than local constant smoothing when there are holes in the support.

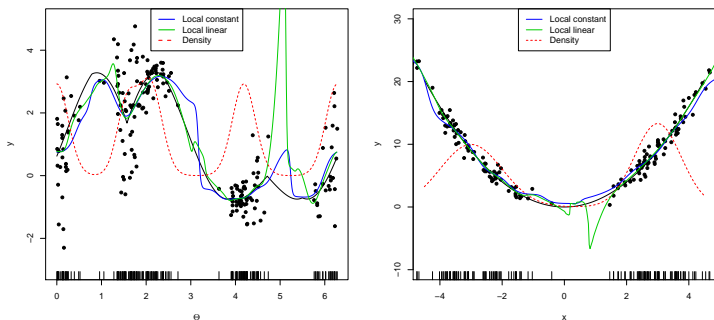


Figure : Local constant and linear estimators with predictor for samples with areas with low density.



## Some notes of caution in smoothing

- 1 Holes in the support and local linear estimation.
- 2 **Nonparametric wild bootstrap:**  $\hat{\varepsilon}_i = Y_i - \hat{m}_{h,p}(\mathbf{X}_i)$ . Versus the parametric one that we have used:  $\hat{\varepsilon}_i = Y_i - m_{\hat{\theta}}(\mathbf{X}_i)$ .

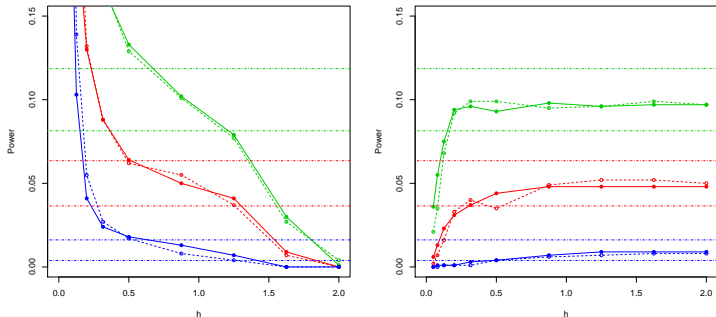


Figure : Sizes for nonparametric and parametric wild bootstraps.



## Some notes of caution in smoothing

- 1 Holes in the support and local linear estimation.
- 2 Nonparametric wild bootstrap:  $\hat{\varepsilon}_i = Y_i - \hat{m}_{h,p}(\mathbf{X}_i)$ .
- 3 Estimation bandwidths for testing. Bandwidths arising from estimation criteria are not always a reasonable option.

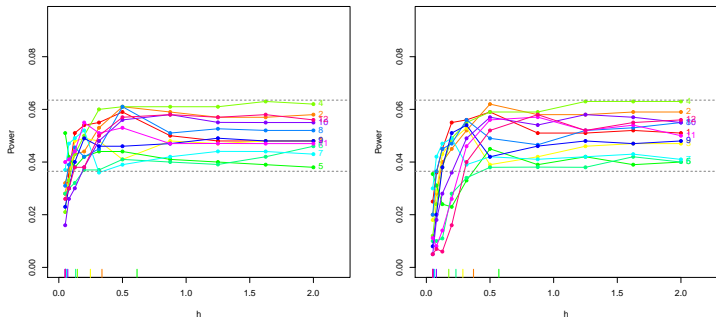


Figure : Sizes for averaged estimation bandwidths for  $p = 0$  and  $p = 1$ .

Concept	Our proposal	Di Marzio <i>et al.</i> (2014)
Taylor expansion	$m(\mathbf{X}_i) \approx m(\mathbf{x}) + \nabla m(\mathbf{x})^T \mathbf{B}_q \mathbf{B}_q^T (\mathbf{X}_i - \mathbf{x})$	$m(\mathbf{X}_i) \approx m(\mathbf{x}) + \theta_{\mathbf{x},i} \boldsymbol{\xi}_{\mathbf{x},i}^T \nabla m(\mathbf{x}),$ $\mathbf{X}_i = \mathbf{x} \cos(\theta_{\mathbf{x},i}) + \boldsymbol{\xi}_{\mathbf{x},i} \sin(\theta_{\mathbf{x},i})$
$\boldsymbol{\mathcal{X}}_{\mathbf{x},1}$ 's $i$ -th row	$(1, \mathbf{B}_q(\mathbf{X}_i - \mathbf{x})^T)_{q+1}$	$(1, \theta_{\mathbf{x},i} \boldsymbol{\xi}_{\mathbf{x},i}^T)_{q+2}$
Bandwidth	$h = \kappa^{-\frac{1}{2}}$	$\kappa = h^{-2}$
Kernel	$L_h(\mathbf{x}, \mathbf{X}_i) = c_{h,q}(L) L \left( \frac{1 - \mathbf{x}^T \mathbf{X}_i}{h^2} \right)$	$K_\kappa(\cos(\theta_i)) = K_\kappa(\mathbf{x}^T \mathbf{X}_i)$
Case $q = 1$	Di Marzio <i>et al.</i> (2009) estimator. If $\mathbf{x} = (\cos \theta, \sin \theta),$ $\mathbf{X}_i = (\cos \Theta_i, \sin \Theta_i),$ $\mathbf{B}_1 = (-\sin \theta, \cos \theta)^T,$ then $\mathbf{B}_1(\mathbf{X}_i - \mathbf{x}) = \sin(\theta - \Theta_i)$	Different from Di Marzio <i>et al.</i> (2009) (usual vs. tangent-normal Taylor expansions)
Bias	$\frac{b_q(L)}{q} \text{tr} [\boldsymbol{\mathcal{H}}_m(\mathbf{x})] h^2$	$\frac{b_2(\kappa)}{2q} \text{tr} [\boldsymbol{\mathcal{H}}_m(\mathbf{x})]$
Variance	$\frac{\lambda_q(L^2) \lambda_q(L)^{-2}}{nh^q f(\mathbf{x})} \sigma^2(\mathbf{x})$	$\frac{\nu_0(\kappa)}{nf(\mathbf{x})} \sigma^2(\mathbf{x})$

Table : Proposals for local linear smoothing.

Alternative proposal

Model	Circular case ( $q = 1$ )						Spherical case ( $q = 2$ )					
	Local constant			Local linear			Local constant			Local linear		
	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$
M1	<b>0.009</b>	<b>0.009</b>	0.013	<b>0.009</b>	<b>0.009</b>	0.013	<b>0.003</b>	<b>0.003</b>	0.007	0.003	0.003	0.007
M2	0.027	0.026	0.041	0.025	<b>0.023</b>	0.068	0.025	0.024	0.063	0.022	<b>0.021</b>	0.068
M3	0.039	0.037	0.063	0.033	<b>0.031</b>	0.038	0.038	0.038	0.067	0.030	<b>0.029</b>	0.047
M4	0.056	0.056	0.253	<b>0.046</b>	<b>0.045</b>	0.274	0.044	0.044	0.045	0.041	<b>0.040</b>	0.043
M5	0.040	0.044	0.044	0.027	0.032	<b>0.025</b>	<b>0.030</b>	<b>0.030</b>	0.065	0.034	0.036	0.042
M6	0.051	0.050	0.059	<b>0.046</b>	0.048	0.114	<b>0.030</b>	<b>0.030</b>	0.057	0.031	0.031	0.033
M7	0.043	0.042	0.320	0.043	<b>0.040</b>	0.317	0.062	0.062	0.062	0.061	0.061	<b>0.060</b>
M8	0.048	0.048	0.586	0.047	<b>0.047</b>	0.484	<b>0.161</b>	0.163	0.803	0.167	0.178	0.779
M9	0.058	0.057	0.793	0.054	<b>0.052</b>	1.068	0.130	0.124	1.095	0.109	<b>0.109</b>	1.368
M10	0.036	0.036	0.102	0.032	<b>0.031</b>	0.079	0.111	0.107	0.527	0.107	<b>0.105</b>	0.676
M11	0.030	0.029	0.094	0.202	<b>0.022</b>	0.040	0.165	0.160	1.272	0.158	<b>0.130</b>	0.679
M12	0.059	0.059	0.293	0.081	<b>0.042</b>	0.604	0.061	0.060	0.073	0.059	<b>0.050</b>	0.054

Table : Empirical ASEs with  $n = 250$ . Significant best combinations of estimator and bandwidth selector are marked in bold. ◀ Bandwidth selection



Model	Circular case ( $q = 1$ )						Spherical case ( $q = 2$ )					
	Local constant			Local linear			Local constant			Local linear		
	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$
M1	<b>0.008</b>	<b>0.008</b>	0.017	<b>0.008</b>	0.009	0.018	<b>0.001</b>	<b>0.001</b>	0.003	<b>0.001</b>	<b>0.001</b>	0.003
M2	0.046	0.046	0.093	0.044	<b>0.042</b>	0.087	0.015	0.015	0.042	0.013	<b>0.013</b>	0.070
M3	0.065	0.066	0.098	0.056	<b>0.054</b>	0.090	0.024	0.024	0.044	<b>0.018</b>	<b>0.018</b>	0.028
M4	0.077	0.077	0.076	0.074	<b>0.074</b>	0.080	0.029	0.029	0.029	0.026	<b>0.026</b>	0.026
M5	0.056	<b>0.055</b>	0.113	0.064	0.066	0.084	<b>0.019</b>	0.019	0.042	0.021	0.023	0.023
M6	<b>0.048</b>	0.049	0.081	0.050	<b>0.049</b>	0.054	<b>0.021</b>	<b>0.021</b>	0.040	0.022	0.021	0.022
M7	0.088	0.088	<b>0.082</b>	0.087	0.087	0.084	0.046	0.046	0.050	0.045	<b>0.045</b>	0.049
M8	<b>0.232</b>	0.254	0.802	0.247	0.279	0.753	<b>0.121</b>	0.121	0.756	0.122	0.125	0.766
M9	0.199	0.175	1.104	0.170	<b>0.162</b>	1.201	0.092	0.090	1.113	0.077	<b>0.076</b>	1.392
M10	0.167	<b>0.153</b>	0.679	0.183	0.155	0.703	0.080	0.079	0.380	0.074	<b>0.073</b>	0.555
M11	0.246	0.217	1.053	0.542	<b>0.192</b>	0.564	0.121	0.120	1.370	0.115	<b>0.095</b>	0.731
M12	0.099	0.096	0.118	0.121	<b>0.083</b>	0.096	0.042	0.042	0.052	0.040	<b>0.035</b>	0.037

Table : Empirical ASEs with  $n = 500$ . Significant best combinations of estimator and bandwidth selector are marked in bold. ◀ Bandwidth selection

Model	Circular case ( $q = 1$ )						Spherical case ( $q = 2$ )					
	Local constant			Local linear			Local constant			Local linear		
	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$	$h_{CV}$	$h_{GCV}$	$h_{PI}$
M1	<b>0.022</b>	0.024	0.033	<b>0.023</b>	0.023	0.034	<b>0.005</b>	<b>0.005</b>	0.007	<b>0.005</b>	0.005	0.007
M2	0.063	0.058	0.078	0.055	<b>0.052</b>	0.086	0.016	0.015	0.027	0.014	<b>0.013</b>	0.076
M3	0.085	0.079	0.124	0.074	<b>0.068</b>	0.083	0.022	0.021	0.037	0.019	<b>0.017</b>	0.022
M4	0.119	0.117	0.344	<b>0.100</b>	<b>0.100</b>	0.330	0.034	0.033	0.146	0.027	<b>0.026</b>	0.220
M5	0.071	0.067	0.093	<b>0.058</b>	0.062	<b>0.059</b>	0.022	0.030	0.026	0.015	0.019	<b>0.014</b>
M6	0.106	0.105	0.116	<b>0.091</b>	0.094	0.183	0.031	0.030	0.036	<b>0.028</b>	0.029	0.087
M7	0.165	0.162	0.309	<b>0.152</b>	<b>0.149</b>	0.304	0.023	0.023	0.321	<b>0.022</b>	<b>0.022</b>	0.320
M8	0.091	<b>0.088</b>	0.814	0.099	0.092	0.617	0.030	0.030	0.377	0.028	<b>0.028</b>	0.367
M9	0.102	<b>0.097</b>	0.854	0.119	0.100	1.052	0.040	0.040	0.761	0.034	<b>0.034</b>	1.041
M10	0.071	0.070	0.180	0.067	<b>0.064</b>	0.134	0.021	0.021	0.059	0.018	<b>0.018</b>	0.051
M11	0.091	0.047	0.147	0.331	<b>0.041</b>	0.081	0.023	0.023	0.062	0.082	<b>0.015</b>	0.025
M12	0.092	0.091	0.409	0.249	<b>0.073</b>	0.800	0.045	0.044	0.202	0.042	<b>0.029</b>	0.478

Table : Empirical ASEs with  $n = 500$ . Significant best combinations of estimator and bandwidth selector are marked in bold. ◀ Bandwidth selection

## Sketch of the proof

◀ Limit distribution of  $T_n$

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2)$$

- 1 Decompose  $T_n = (T_{n_1} + T_{n_2} - 2T_{n_3})(1 + o_{\mathbb{P}}(1))$  using the equivalent kernel formulation:

$$T_{n_1} = \int_{\Omega_q} \left( \sum_{i=1}^n L_p^*(\mathbf{x}, \mathbf{X}_i) (Y_i - m_{\theta_0}(\mathbf{X}_i)) \right)^2 f(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}),$$

$$T_{n_2} = \int_{\Omega_q} (\mathcal{L}_{h,p}(m_{\theta_0} - m_{\hat{\theta}})(\mathbf{x}))^2 f(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}),$$

$$T_{n_3} = \int_{\Omega_q} (\hat{m}_{h,p}(\mathbf{x}) - \mathcal{L}_{h,p}m_{\theta_0}(\mathbf{x})) \mathcal{L}_{h,p}(m_{\theta_0} - m_{\hat{\theta}})(\mathbf{x}) f(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}).$$

## Sketch of the proof

◀ Limit distribution of  $T_n$

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2)$$

- ① Decompose  $T_n = (T_{n_1} + T_{n_2} - 2T_{n_3})(1 + o_{\mathbb{P}}(1))$  using the equivalent kernel formulation:

$$T_{n_1} = \int_{\Omega_q} \left( \sum_{i=1}^n L_p^*(\mathbf{x}, \mathbf{X}_i) (Y_i - m_{\theta_0}(\mathbf{X}_i)) \right)^2 f(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}),$$

$$T_{n_2} = \int_{\Omega_q} (\mathcal{L}_{h,p}(m_{\theta_0} - m_{\hat{\theta}})(\mathbf{x}))^2 f(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}),$$

$$T_{n_3} = \int_{\Omega_q} (\hat{m}_{h,p}(\mathbf{x}) - \mathcal{L}_{h,p}m_{\theta_0}(\mathbf{x})) \mathcal{L}_{h,p}(m_{\theta_0} - m_{\hat{\theta}})(\mathbf{x}) f(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}).$$

- ②  $nh^{\frac{q}{2}}T_{n_2} = o_{\mathbb{P}}(1)$  and  $nh^{\frac{q}{2}}T_{n_3} = o_{\mathbb{P}}(1)$  by  $\sqrt{n}$ -consistency of  $\hat{\theta}$ .

## Sketch of the proof

◀ Limit distribution of  $T_n$

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x}) \omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2)$$

- 1 Decompose  $T_n = (T_{n_1} + T_{n_2} - 2T_{n_3})(1 + o_{\mathbb{P}}(1))$  using the equivalent kernel formulation:

$$T_{n_1} = \int_{\Omega_q} \left( \sum_{i=1}^n L_p^*(\mathbf{x}, \mathbf{X}_i) (Y_i - m_{\theta_0}(\mathbf{X}_i)) \right)^2 f(\mathbf{x})w(\mathbf{x}) \omega_q(d\mathbf{x}),$$

$$T_{n_2} = \int_{\Omega_q} (\mathcal{L}_{h,p}(m_{\theta_0} - m_{\hat{\theta}})(\mathbf{x}))^2 f(\mathbf{x})w(\mathbf{x}) \omega_q(d\mathbf{x}),$$

$$T_{n_3} = \int_{\Omega_q} (\hat{m}_{h,p}(\mathbf{x}) - \mathcal{L}_{h,p}m_{\theta_0}(\mathbf{x})) \mathcal{L}_{h,p}(m_{\theta_0} - m_{\hat{\theta}})(\mathbf{x}) f(\mathbf{x})w(\mathbf{x}) \omega_q(d\mathbf{x}).$$

- 2  $nh^{\frac{q}{2}}T_{n_2} = o_{\mathbb{P}}(1)$  and  $nh^{\frac{q}{2}}T_{n_3} = o_{\mathbb{P}}(1)$  by  $\sqrt{n}$ -consistency of  $\hat{\theta}$ .

- 3 Split  $T_{n_1} = T_{n_1}^{(1)} + T_{n_1}^{(2)} + 2T_{n_1}^{(3)}$  where  $nh^{\frac{q}{2}}T_{n_1}^{(2)} = o_{\mathbb{P}}(1)$  and  $nh^{\frac{q}{2}}T_{n_1}^{(3)} = o_{\mathbb{P}}(1)$ . Finally, by de Jong (1987)'s CLT,

$$nh^{\frac{q}{2}} \left( T_{n_1}^{(1)} - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x}) \omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2).$$

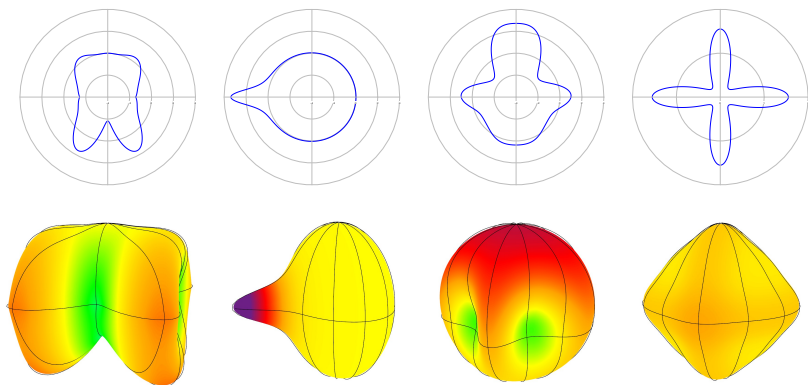


Figure : Deviations  $\Delta_1$ ,  $\Delta_2$  and  $\Delta_3$  (from left to right, first three columns) and conditional standard deviation for the heteroskedastic noise (fourth column). [◀ Simulation study](#)

## Theorem (Bootstrap consistency)

← Calibration in practice

Under conditions LL1–LL4, GF1–GF5 and under the hypothesis  $H_{1L}$ ,

$$nh^{\frac{q}{2}} \left( T_n^* - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma^2(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu^2)$$

with probability one.

► A **bootstrap** analogue of **condition GF1** is required:

**GF5** Under  $H_{1L}$ , and for  $\mathbf{X}_1, \dots, \mathbf{X}_n$ , there exists an estimator  $\hat{\boldsymbol{\theta}}^*$  such that  $\hat{\boldsymbol{\theta}} - \hat{\boldsymbol{\theta}}^* = \mathcal{O}_{\mathbb{P}^*} \left( n^{-\frac{1}{2}} \right)$ .

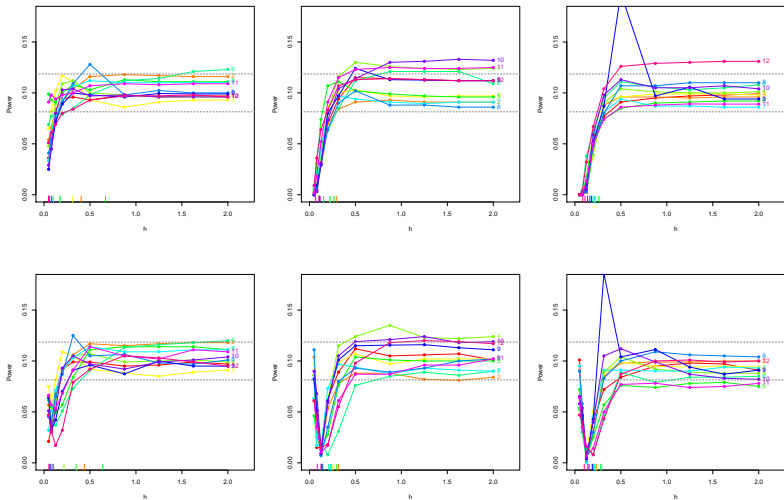


Figure : Empirical sizes for  $\alpha = 0.10$  with  $p = 0$  (upper row) and  $p = 1$  (lower row). Columns:  $q = 1, 2, 3$  and  $n = 100, 250, 500$ . ← Simulation



Model	Regression function	Density	Noise	Deviation
M1	$m(\mathbf{x}) = m$	D1	Het.	$0.5\Delta_1(\mathbf{x})$
M2	$m(\mathbf{x}) = m + \boldsymbol{\eta}^T \mathbf{x}$	D2	Het.	$-0.25\Delta_1(\mathbf{x})$
M3	$m(\mathbf{x}) = m + \boldsymbol{\eta}^T \mathbf{x} + \boldsymbol{\gamma}^T (x_1^2, \dots, x_q^2)$	D3	Het.	$-\Delta_1(\mathbf{x})$
M4	$m(\mathbf{x}) = m + a(x_{q+1}^2 - x_q^3) + bx_1x_2$	D4	Het.	$-0.25\Delta_1(\mathbf{x})$
M5	$m(\mathbf{x}) = m + ax_1^4 + b\left(\frac{3}{2} - x_1\right)^{-\frac{1}{2}}$	D5	Het.	$-\Delta_2(\mathbf{x})$
M6	$m(\mathbf{x}) = ae^{bx_2} \log(cx_{q+1}  x_1 ) + d \max( x_1 ,  x_2 )$	D6	Het.	$-3\Delta_2(\mathbf{x})$
M7	$m(\mathbf{x}) = m + d_1 f_{vM}(\mathbf{x}, (\mathbf{0}_q, 1), \kappa_1) - d_2 f_{Ca}(\mathbf{x}, (\mathbf{0}_q, 1), \kappa_2)$	D1	Hom.	$-0.3\Delta_2(\mathbf{x})$
M8	$m(\mathbf{x}) = m + af_{SN}(\max(-\mathbf{x}), b, c, d)$	D2	Hom.	$-0.4\Delta_2(\mathbf{x})$
M9	$m(\mathbf{x}) = m + af_{SN}(\prod_{i=1}^{q+1} x_i, b, c, d)$	D3	Hom.	$0.1\Delta_3(\mathbf{x})$
M10	$m(\mathbf{x}) = m + a \sin(2\pi x_2) + b \cos(2\pi x_1)$	D4	Hom.	$0.25\Delta_3(\mathbf{x})$
M11	$m(\mathbf{x}) = m + a \sin(2\pi bx_1 x_{q+1})$	D5	Hom.	$-1.5\Delta_3(\mathbf{x})$
M12	$m(\mathbf{x}) = m + a \sin(2\pi b(2 + x_{q+1})^{-1})$	D6	Hom.	$0.3\Delta_3(\mathbf{x})$

Table : Simulation scenarios. [◀ Models](#)

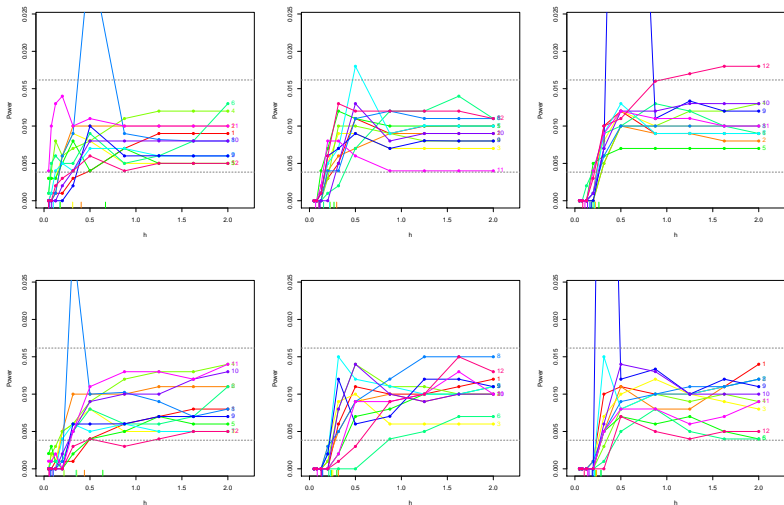


Figure : Empirical sizes for  $\alpha = 0.01$  with  $p = 0$  (upper row) and  $p = 1$  (lower row). Columns:  $q = 1, 2, 3$  and  $n = 100, 250, 500$ . ◀ Simulation

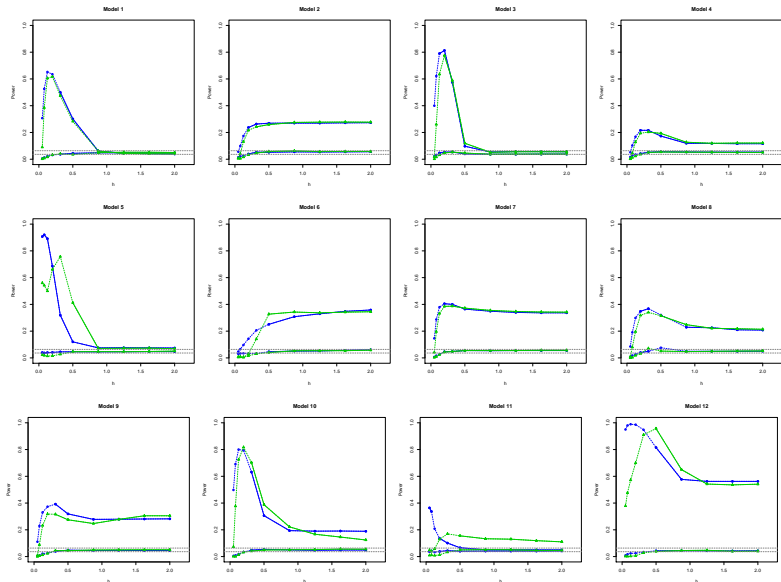


Figure : Empirical powers for  $\alpha = 0.05$  with  $p = 0$  (blue) and  $p = 1$  (green), for  $q = 1$  and  $n = 100$ . ◀ Simulation

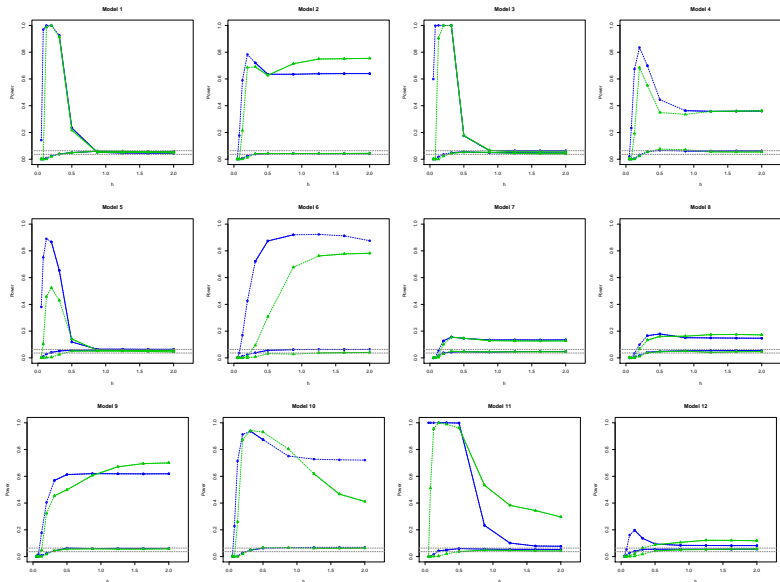


Figure : Empirical powers for  $\alpha = 0.05$  with  $p = 0$  (blue) and  $p = 1$  (green), for  $q = 2$  and  $n = 250$ . ◀ Simulation

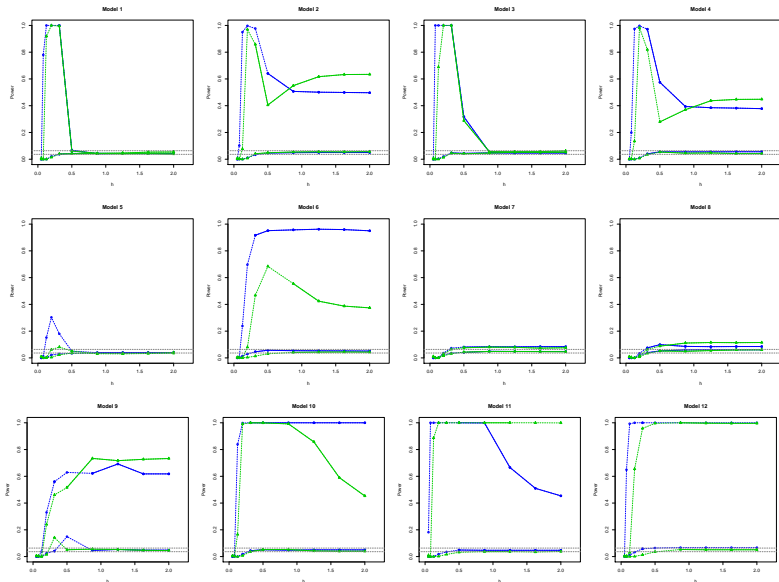


Figure : Empirical powers for  $\alpha = 0.05$  with  $p = 0$  (blue) and  $p = 1$  (green), for  $q = 3$  and  $n = 500$ . ◀ Simulation